













3D BAG Developers' meeting 13-11-2024 online 13:00-15:30







3DBAG Team

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Ivan Paden
Gina Stavropoulou
Jantien Stoter





Part 0 -

Introduction to 3DBAG and this meeting



House Rules

- Make sure you are muted during the presentations.
- If you have any questions, send them to the chat.
 Then we can answer them during the QA sessions.
- There will be some **feedback sessions** where you will be asked to answer a few questions. You can use either your browser or your phone to participate.

What is the 3DBAG?

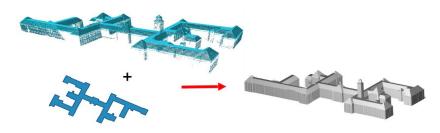
Baseregister Addresses and Buildings

- Dataset with 3D models for all ~ 10 million
 BAG-buildings in NL
 - Reconstructed from open govern. data
 - BAG footprint + LiDAR Point cloud (AHN)
 - Available as open data
- 2. Software behind the dataset + hardware

Built and maintained by







Automated 3D reconstruction of LoD2 and LoD1 models for all 10 million buildings of the netherlands.

R Peters, B Dukai, S Vitalis, J van Liempt, J Stoter.

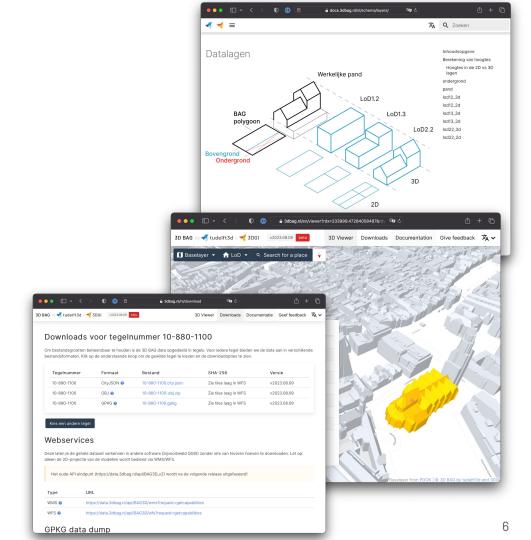
Photogrammetric Engineering and Remote Sensing 88(3), 2022.



3DBAG available

Via 3dbaq.nl

- 3D viewer
 - Directly view and inspect data
 - Also works on mobile
- Download data at different LoDs
 - available in common GIS/3D formats
- Documentation
 - Describing the dataset and how to use it



History and status 3DBAG



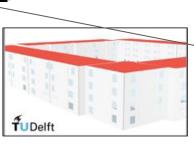


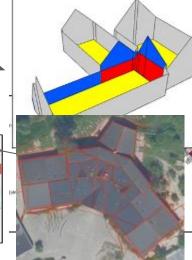
- Started as research projects (since 2018)
- Testbed for 3D geoinformation
 - Push state-of-the-art 3D building reconstruction
 - Push 3D innovations in urban applications (by us + others)
 - Push use of open data standards (CityJSON)



- Updates + improvements +
- New features from research: volume, areas wall/roof/floor, nr floors, party walls
- Ongoing research:
 - o Add openings from oblique images, use other data sources, use in BIM
- Wide use: per month:
 - ~ 100 000 tiles downloads
 - ~ 850 000 webservice queries

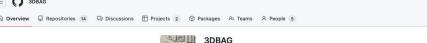








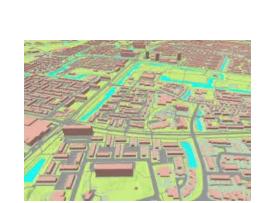
3DBAG status

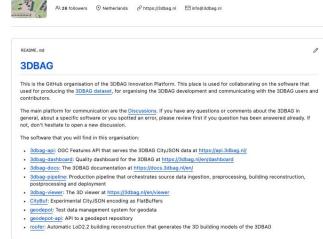


Widely adopted; passed research phase

- WaU-subsidy (Kadaster) for software refactoring
 - Easier for maintenance, new releases, innovations and other developers
 - Performed by 3DGI and TU3D
 - o => https://github.com/3DBAG

- Looking for stable role of data and software
 - While keeping innovation power
 - Align with 3D Basis-dataset of Kadaster





3DBAG Innovatieplatform

Keep data (and updates) available

Collaboration in further innovations

Securing the future of 3DBAG:

Maintain OS software













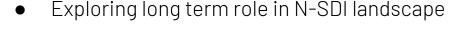




Netherlands Enterprise Agency







- Activities 2024:
 - Start community of 3DBAG data users in NL
 - Start community of software users & developers: today!
 - also outside NL
 - AHN5 update (3/3 NL)





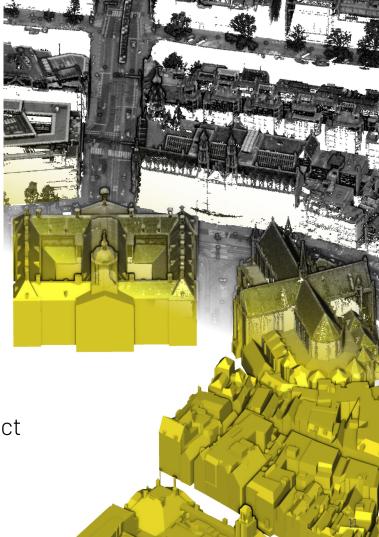
Today's meeting:

Goal: start developers community

- Present key components 3DBAG (plans+roadmap)
- Hear your ideas/feedback for future devs
- Discuss possible structure/organisation of dev community
 - o work processes, communication platform, meetings

Target audience

- Potential users of the 3DBAG software
- 2. Developers, potential contributors to 3DBAG project
 - More technical talk near the end of the session
 - Both NL and abroad!



Overview of this meeting

- Part 1: Build your own 3DBAG (for users of the software)
 - Overview of the different software components and how to use them

5 minute break



Part 2: 3DBAG data access/processing for developers

5 minute break

Part 3: Road Map and Community

During the presentations put your questions in the chat!

3DBAG

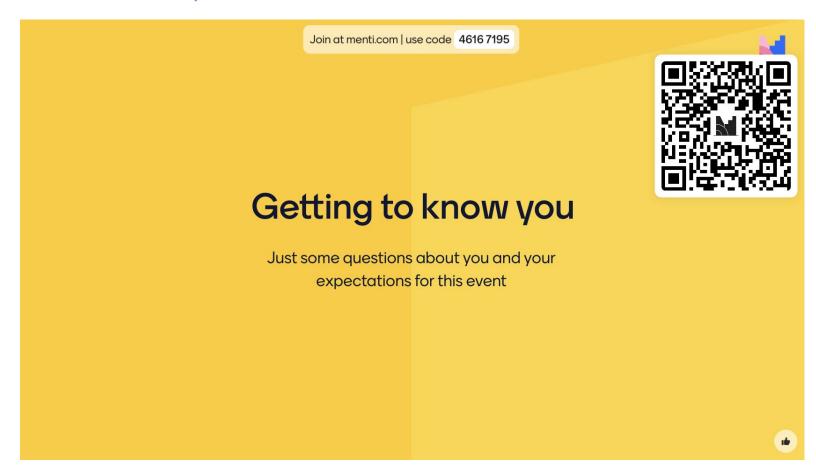
This is the GitHub organisation of the 3DBAG innovation Platform. This place is used for collaborating on the software that used for producing the 3DBAG dataset, for organising the 3DBAG development and communicating with the 3DBAG users and contributors.

The main platform for communication are the <u>Discussions</u>. If you have any questions or comments about the 3DBAG in general, about a specific software or you spotted an error, please review first if you question has been answered already. If not, don't hesitate to open a new discussion.

The software that you will find in this organisation:

- 3dbag-api: OGC Features API that serves the 3DBAG CityJSON data at https://api.3dbag.nl/
- 3dbag-dashboard: Quality dashboard for the 3DBAG at https://3dbag.nl/en/dashboard
- 3dbag-docs: The 3DBAG documentation at https://docs.3dbag.nl/en/
- 3dbag-pipeline: Production pipeline that orchestrates source data ingestion, preprocessing, building reconstruction, postprocessing and deployment
- 3dbag-viewer: The 3D viewer at https://3dbag.nl/en/viewer
- · CityBuf: Experimental CityJSON encoding as FlatBuffers
- geodepot: Test data management system for geodata
- geodepot-api: API to a geodepot repository
- roofer: Automatic LoD2.2 building reconstruction that generates the 3D building models of the 3DBAG

Time for some questions...



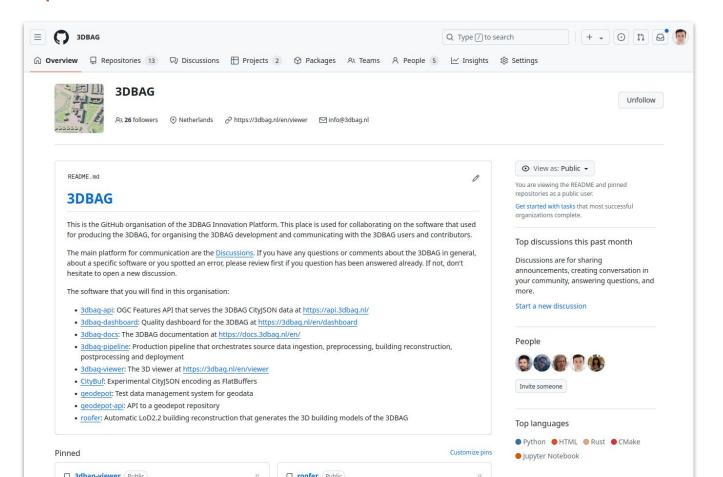
Part I – Build your own 3DBAG



3DBAG tools overview

3DBAG repositories

https://github.com/3DBAG



3DBAG repositories

https://github.com/3DBAG

Experiments

CityBuf

Develop

- geodepot
- geodepot-api

Generate

- *-pipeline
- roofer

Publish

- *-api
- *-dashboard
- *-docs
- *-viewer

3DBAG tech stack



































3DBAG tech stack











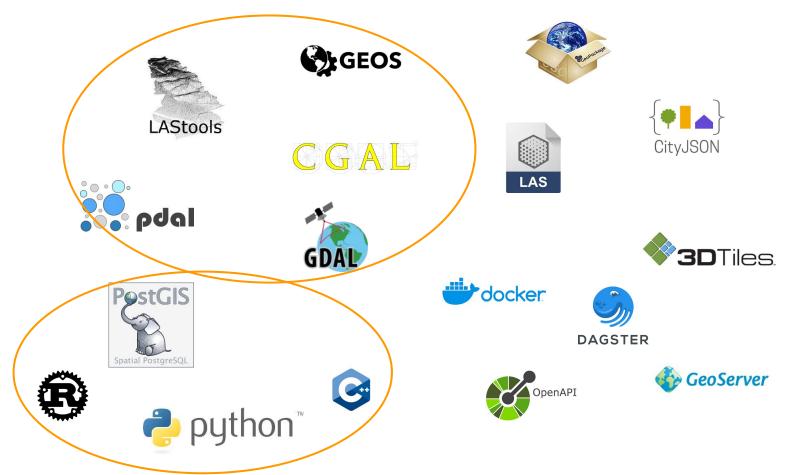




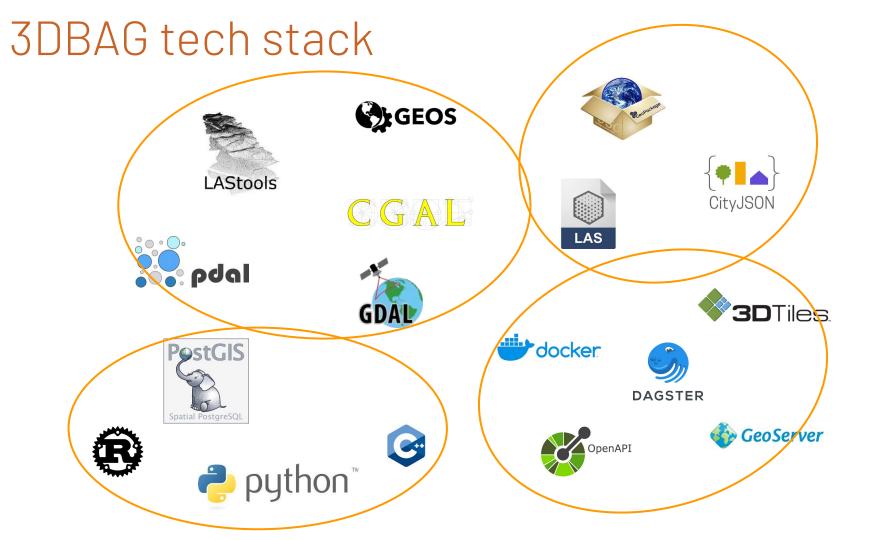




3DBAG tech stack



3DBAG tech stack GEOS **LAStools** CityJSON CGAL LAS pdal GDAL **3D**Tiles. **docker PostGIS DAGSTER** Spatial PostgreSQL GeoServer python*



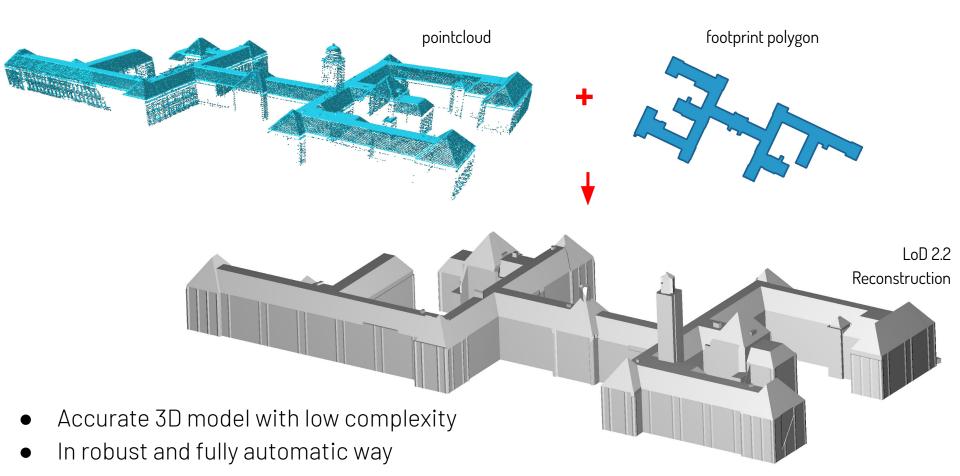
roofer

What is it?

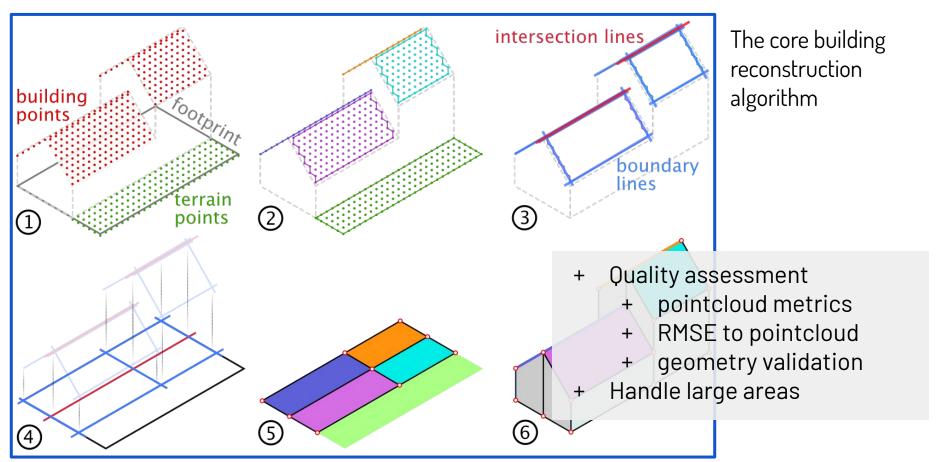
roofer is an application to do large scale automatic LoD2 building reconstruction

* core reconstruction algorithm also available through Python and C++ API

What does it do?



What does it do?



History of building reconstruction algorithm

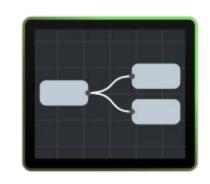
- Originally developed as a plugin to Geoflow
- Geoflow = research/algorithm development tool for 3D geodata.
 - Mix of low level 'building blocks' and high level flowchart logic to develop an algorithm
- Geoflow allowed for interactive and visual experimentation with single buildings.
- Great for developing the reconstruction algorithm.



Geoflow limitations

But...

- Geoflow itself was a prototype
 - not really designed for production use
- Difficult to reconstruct large areas due to architectural limitations.
 - Pre-tiling data was needed
 - Multithreading through external tools.
- We made it work, but it was very brittle due to many 'hacks' to work around limitations
 - Silent failures
 - Flowchart architecture had little added value in production use
- Development and maintenance was not sustainable

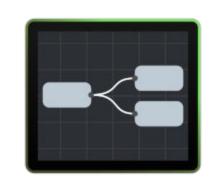


Geoflow limitations

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We learned a lot, but time to decouple the building reconstruction algorithm....



geoflow-bundle → roofer

roofer is a single application focused purely on automatic building reconstruction

- in a reliable way
 - \circ each input feature \rightarrow one output feature
 - o no silent failures
- focus on usability
 - o minimise preprocessing needs,
 - smartly select subset of large inputs
 - no pre-tiling
 - o proper validation of input data and arguments
 - o clear error messages

geoflow-bundle → roofer

roofer is a single application focused purely on automatic building reconstruction

- for efficient large scale reconstruction
 - built-in multithreading
 - memory efficient
- capable but simple design that is easy to maintain
 - single code base, no separate plugins
 - o minimal external dependencies

roofer architecture

modules and external dependencies

Core

Reconstruction algorithm

CGAL fmt

Extra

Machinery for CLI app

GDAL/OGR
GEOS
LAStools
nlohmann_json
val3dity

roofer architecture

modules and external dependencies



Reconstruction algorithm

CGAL fmt

roofer API (C++/Python)

Extra

Machinery for CLI app

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roofer architecture

modules and external dependencies

Core

Reconstruction algorithm

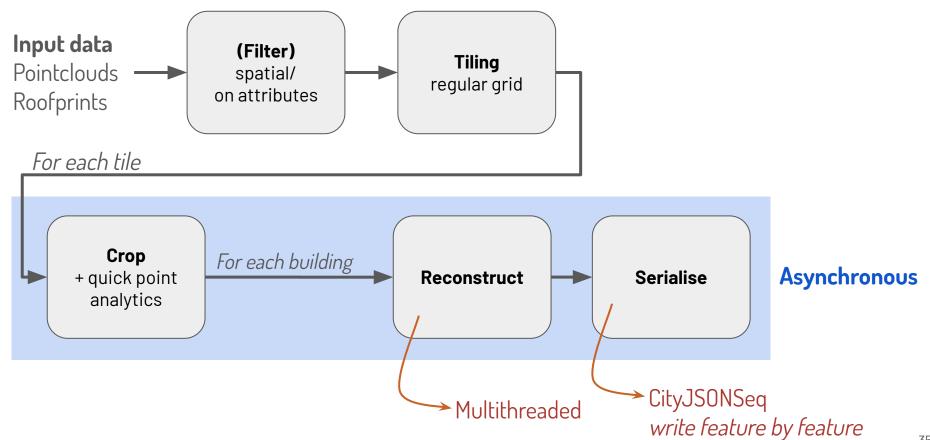
CGAL fmt

Extra

Machinery for CLI app

GDAL/OGR GEOS LAStools nlohmann_json val3dity roofer application

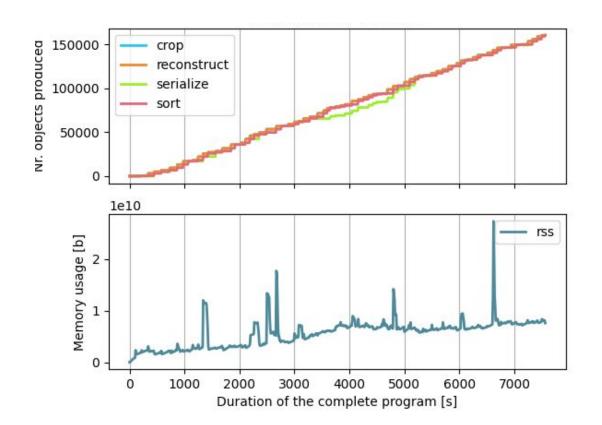
roofer processing pipeline (CLI app)



roofer data pipeline (CLI app)

In practice

- All steps happen in parallel
- Memory usage is stable



How to use roofer?

- Through API (Python/C++)
 - a. developers
- 2. Through CLI application
 - a. most people

Roofer Python API



Python example:

```
import rooferpy
# ... get the input pointcloud and footprint polygon for your building
# Set the reconstruction configuration
roofer config = rooferpy.ReconstructionConfig()
roofer config.complexity factor = 0.7 # Change the default values if needed
# Reconstruct
print("Reconstructing building...")
meshes = rooferpy.reconstruct(points roof, points terrain, footprint, roofer config)
```

`pip install roofer` is coming soon

Roofer C++ API



C++ example:

```
#include <roofer/roofer.h>
// ... get the input pointcloud and footprint polygon for your building
auto meshes =
    roofer::reconstruct(points_roof, points_terrain, footprints.front(),
{.complexity_factor = 0.7});
```

Add to your project via CMake





Designed to efficiently reconstruct large areas with many buildings

- Capable of handling large input datasets
- Using multithreading for efficient computation
- Outputs 3D models as <u>CityJSONSequence</u>

Basic usage:

\$ roofer pointcloud.las roofprints.gpkg output_folder/

Creates output_folder/ with CityJSONSeq files



Designed to efficiently reconstruct large areas with many buildings

- Capable of handling large input datasets
- Using multithreading for efficient computation
- Outputs 3D models as <u>CityJSONSequence</u>

Usage select subset of large input datasets:

```
$ roofer
    /folder/with/all/LAZ/of/NL/
    "PG:dbname='NL' host='localhost' tables='roofprints'"
    output_folder/
    --box 0 0 100 100
    --filter "YearOfConstruction>2000"
```



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Usage select subset of large input datasets:

```
$ roofer
```

```
/folder/with/all/LAZ/of/NL/
"PG:dbname='NL' host='localhost' tables='roofprints'"
output_folder/
```

--box 0 0 100 100

--filter "YearOfConstruction>2000"

Country wide datasets

Subset on bounding box + attribute



Designed to efficiently reconstruct large areas with many buildings

- Capable of handling large input datasets
- Using multithreading for efficient computation
- Outputs 3D models as <u>CityJSONSequence</u>

Usage select subset of large input datasets:

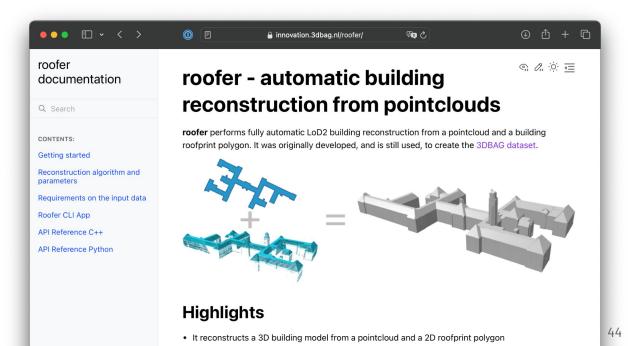
```
$ roofer
```

```
/folder/with/all/LAZ/of/NL/
"PG:dbname='NL' host='localhost' tables='roofprints'"
output_folder/
```

Country wide datasets

Current status

- Still under active development, 95% done
- Documentation is available
- develop-branch can be used, we test before pushing



Near term roadmap: release v1.0

TODO for roofer v1.0:

- Thoroughly test with next 3DBAG data release
 - o fix any bugs we encounter.
- Some more input validation prior to starting processing (CLI app)
- Set up automated build and publishing of binaries (Windows, Linux, macOS)
- Make roofer Python binding pip-installable
- Expected this year

Roadmap after v1.0

Usability improvements:

- Implement multithreading for point cloud reading
- More tiling options
- Ability to execute only cropping or only reconstruction, with intermediate data written to disk
- GUI
- CityBuf output

Roadmap after v1.0

Trivial improvements building reconstruction algorithm:

- Improved plane detection (allow assigning points to multiple planes)
 - Improve reconstruction result for low point density scenarios
- Merge adjacent co-planar faces in output mesh
 - Remove unnecessary faces

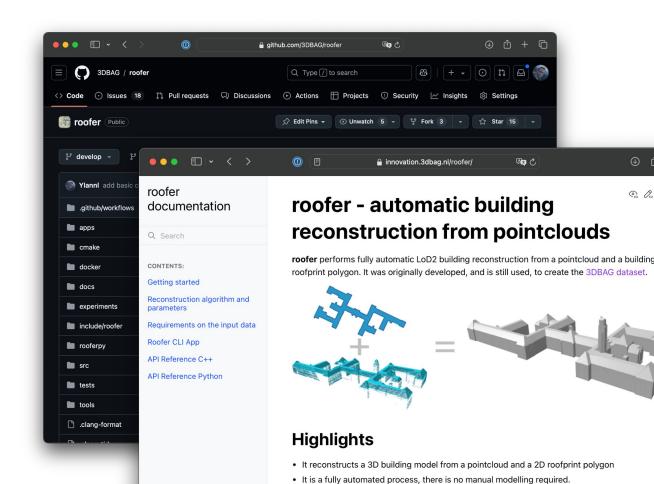
Roadmap after v1.0

Items that require (significant) research and experimentation

- Reduce reliance on accurate building roofprints
 - Rely more on the point cloud data instead
- Incorporate ideas of other building reconstruction methods (eg. City3D, SimpliCity)
 - o One goal: Improve regularisation in geometry
- Enhance input elevation data using deep learning (see <u>RoofDiffusion</u>)
 - More robustness against occlusion gaps in pointcloud
 - possibly remove automatic vegetation over building

Try it

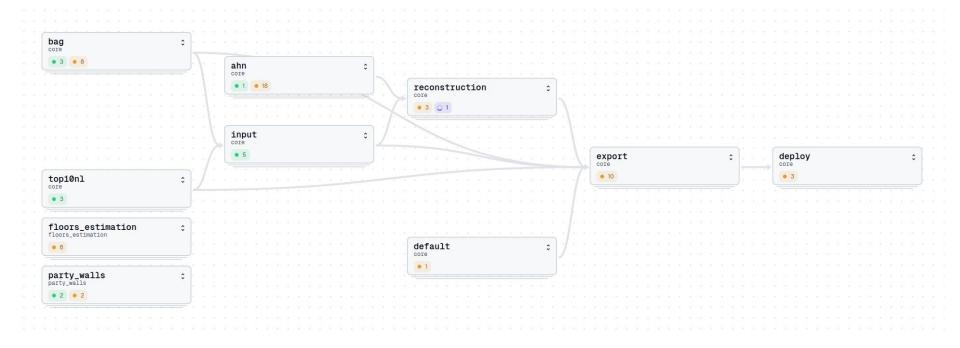




QA session

3dbag-pipeline

What is it?

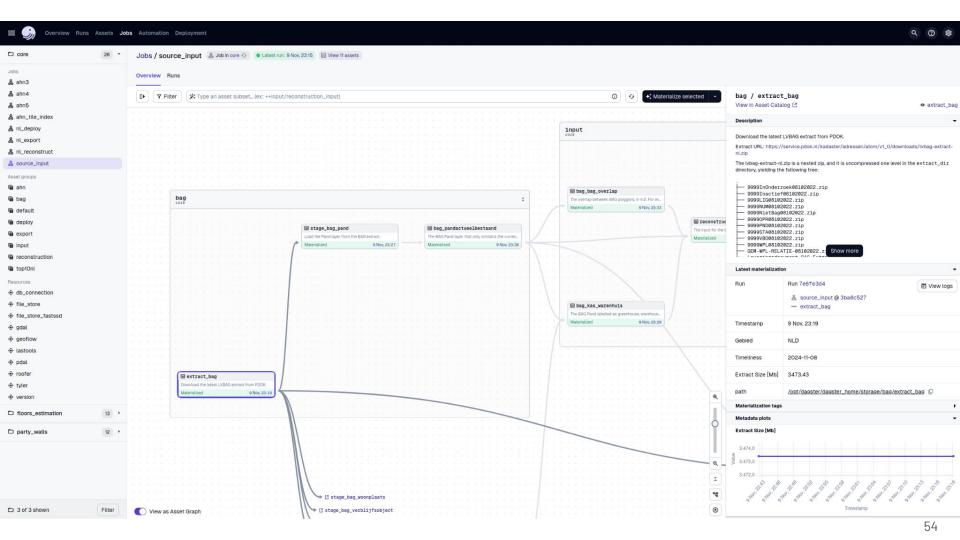


Built with Dagster

- Open source data orchestration platform (Apache-2.0)
- Write regular python code + dagster on top
- Concepts:
 - assets
 - o jobs
 - resources
 - o runs



https://dagster.io



Source Data

BAG https://www.kadaster.nl/bag

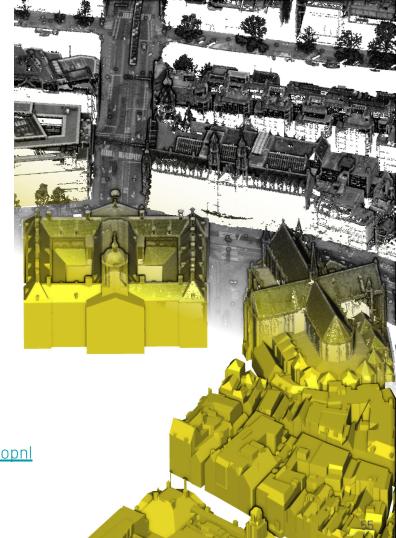
up-to-date building polygons + attributes largest extent → roofprint + underground positional accuracy 30cm

AHN https://ahn.nl

classified point cloud positional accuracy ~23cm (height and planimetric) 8-15 pts/m2 for buildings occlusion and other no-data areas

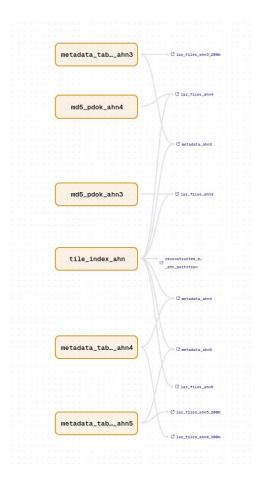
TOP10NL https://www.kadaster.nl/zakelijk/producten/geo-informatie/topnl

topographical map with greenhouse classification



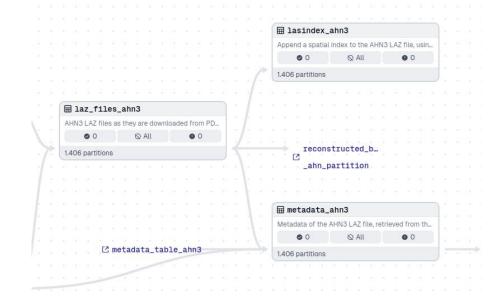
ahn_tile_index

- download AHN tile index
- prepare metadata storage
- download AHN checksums



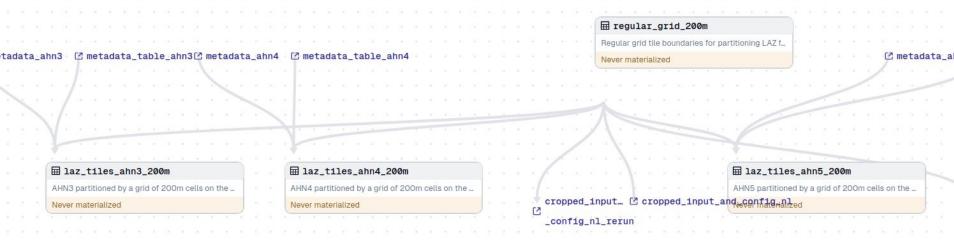
ahn3/4/5

- download the LAZ files
- index the files with lasindex
- compute metadata
- partitioned by AHN tile



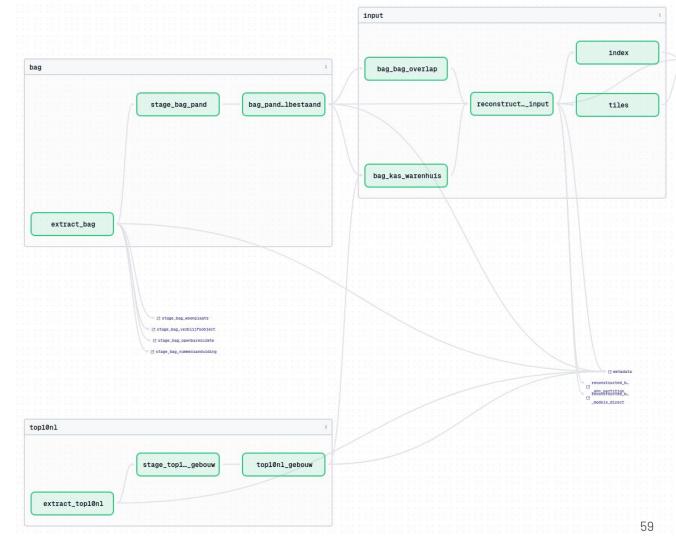
ahn_tiles_200m

• tile up the LAZ files to 200m tiles



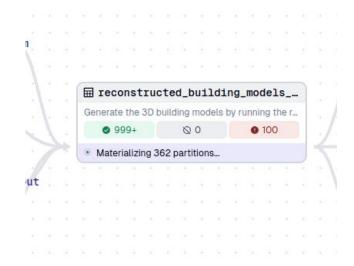
source_input

- 2D vector sources
- download, extract
- stage and transform in PostgreSQL
- combine input table
- tiling



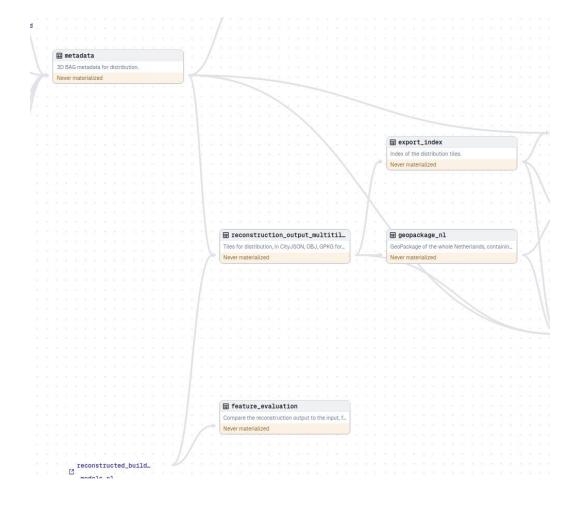
nl_reconstruct

- run reconstruction
- partitioned by 2D input tile



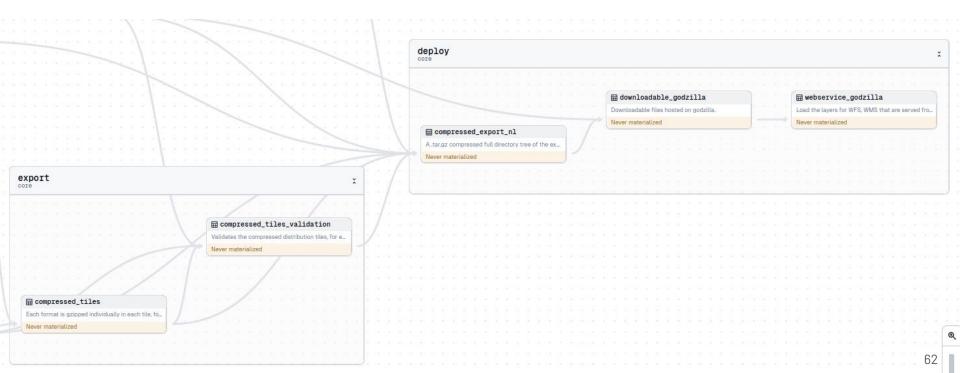
nl_export

- format conversion
- compile metadata
- calculate reconstruction rate



nl_deploy

- compress and validate
- deploy to webserver



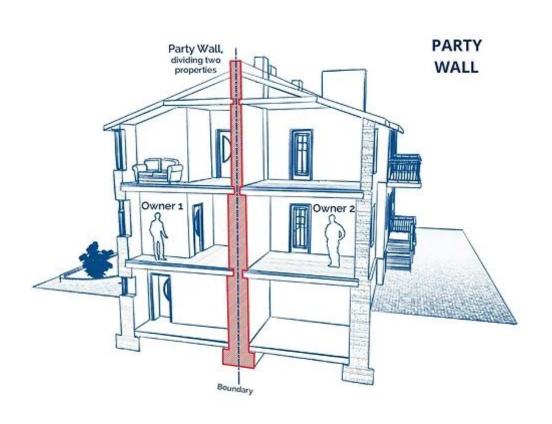
Extensions

floors_estimation

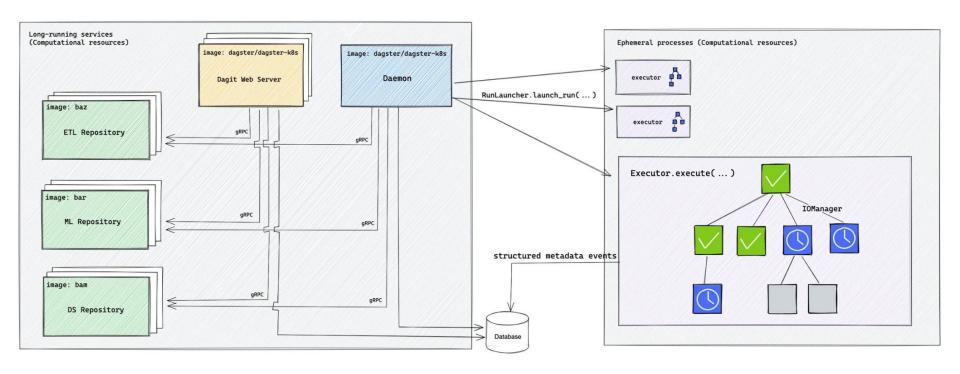
- Estimate the nr. of floors
- Accurate up to 5 floors
 - Not enough training data for tall buildings (random forest regression)
- Computed from CityJSON Features

party_walls

- Compute the area of surfaces, incl. shared walls (party walls)
- Computed from CityJSON tiles



Architecture overview (Dagster)



https://docs.dagster.io/deployment/overview

Architecture overview

Mono-repo with **subpackages**:

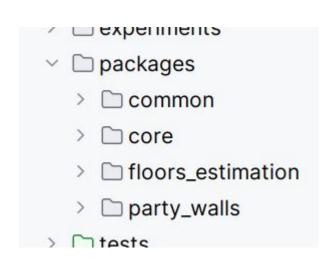
common package for functionality that is used by all workflow packages

Workflow packages contain the pipeline logic:

core The core 3DBAG data

party_walls Party walls calculation

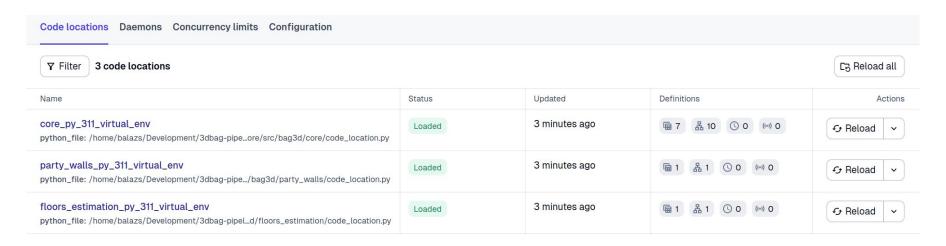
floors_estimation Nr. of floors estimation



Architecture overview

Each workflow package in an isolated virtual environment ("Code Location").

- + Helps us avoid dependency hell
- + Dagster uses gRPC for communicating with the code locations \rightarrow cannot pass execution results

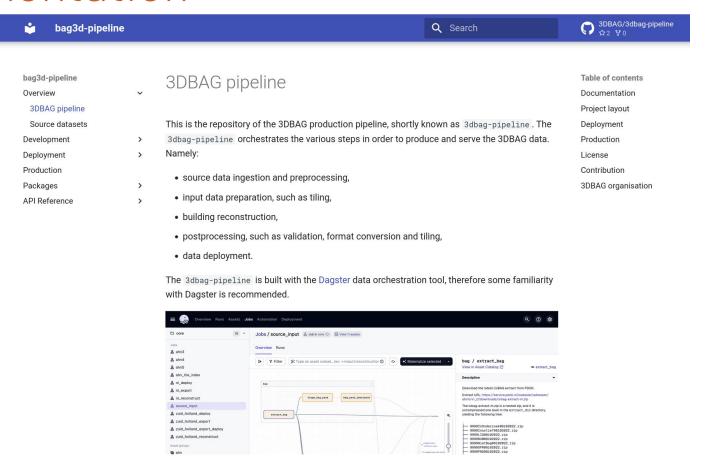


Deployment

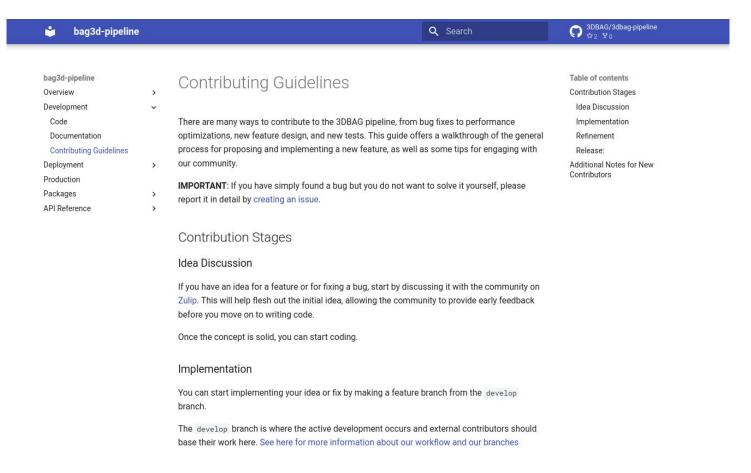
- use docker
 - multi-container setup
 - o all tools built into the base image
 - o each package in its own image
- compose file in repo
 - used for testing on GH Actions
 - o also for local dev

native setup also possible, but complicated

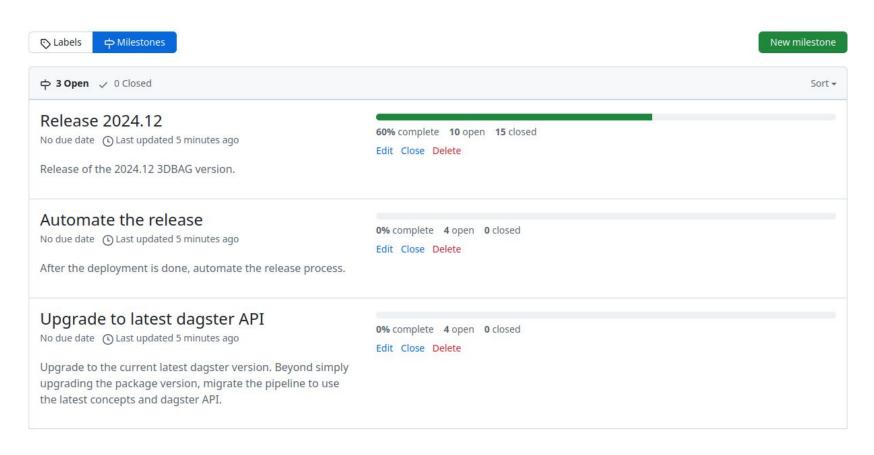
Documentation



Contribution guidelines



Roadmap



Roadmap - 2024.12 3DBAG release

- Integrate the new Roofer
- Integrate AHN5
- Update to the latest Dagster API
- Improve developer experience
 - various levels of testing
 - o C
 - deployment
 - o guidelines and tutorials
- Improve automation

QA session

Time for a 5' break! We will resume at 14:35

Next up: Data Access

Part II - Data access



CityJSON

How to get the 3DBAG data?

Attributes

b3 azimut b3_bag_bag_overlap b3_bouwlagen b3_dak_type b3 dd id b3_h_dak_50p b3_h_dak_70p b3 h dak max b3 h dak min b3 h maaiyeld b3_hellingshoek b3 kas warenhuis b3 kwaliteitsindicator b3 mutatie ahn3 ahn4 b3 nodata fractie ahn3 b3 nodata fractie ahn4 b3 nodata radius ahn3 b3 nodata radius ahn4 b3_pand_deel_id

b3_opp_buitenmuur b3_opp_dak_plat b3_opp_dak_schuin b3_opp_grond b3_opp_scheidingsmuur b3_puntdichtheid_ahn3 b3_puntdichtheid_ahn4 b3_pw_bron b3_pw_datum b3_pw_selectie_reden b3_reconstructie_onvolledig b3 rmse lod12 b3 rmse lod13 b3 rmse lod22 b3_val3dity_lod12 b3_val3dity_lod22 b3 volume lod12 b3 volume lod13 b3 volume lod22

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File formats & Services

Individual tile formats







Full dataset



Web Services





API (3D)

File formats & Services

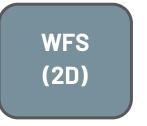
Individual tile formats



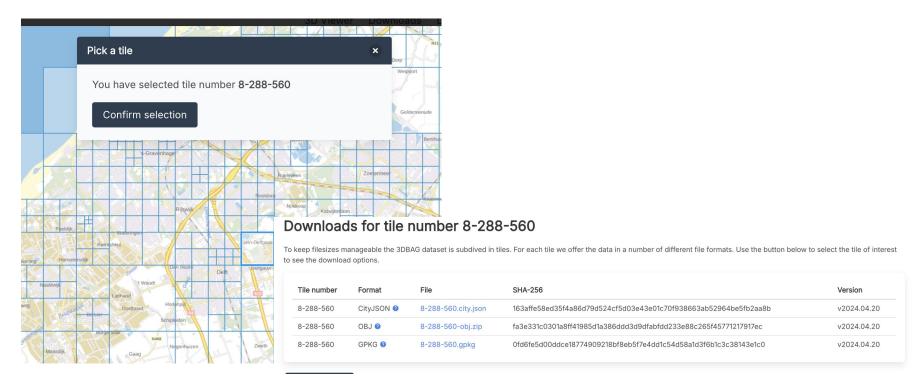
Full dataset

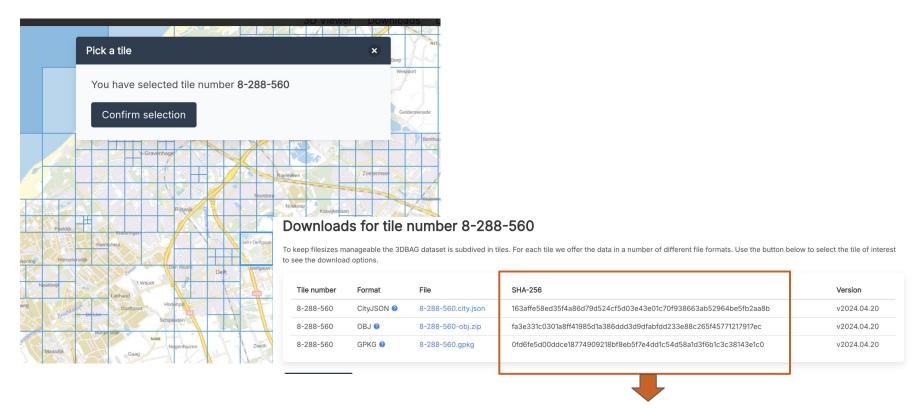


Web Services



WMS (2D) API (3D)





Integrity Verification

All tiles within a bbox: Use the complete tile index (FlatGeoBuf)

```
tile_id': '6/288/672',
    'cj_sha256': 'b932ca1a5d10cca49f37d053fba6116c7ac33b18afc006f64cabcf20aee77d6d',
    'gpkg_sha256': '3e31da3d82100fbcb9bf867756ec056fd238b23d432e1bd1ba93ea8a564cfee0',
    'obj_sha256': '90e58b5ea58463a3d0a12980bb7cd1a238dcfd3406ce13fb1472811a2aa5704c',
    'cj_download': 'https://data.3dbag.nl/v20240420/tiles/6/288/672/6-288-672.city.json.gz',
    'gpkg_download': 'https://data.3dbag.nl/v20240420/tiles/6/288/672/6-288-672.gpkg.gz',
    'obj_download': 'https://data.3dbag.nl/v20240420/tiles/6/288/672/6-288-672-obj.zip'
}
```

All tiles within a bbox: Use the complete tile index (FlatGeoBuf)

Python snippet:

```
from pathlib import Path
from urllib.request import urlretrieve
import flatgeobuf as fgb
outdir = Path("gpkg tiles"); outdir.mkdir(exist ok=True)
tile ids = fgb.HTTPReader('https://data.3dbag.nl/v20240420/tile index.fgb',
bbox=(84000, 477000, 86000, 478000))
for tile id in tile ids:
   url = tile id.properties['gpkg download']
   urlretrieve(url, outdir / url.split('/')[-1])
```

All tiles within a bbox: Use the complete tile index (FlatGeoBuf)

Python snippet:

```
from pathlib import Path
from urllib.request import urlretrieve
import flatgeobuf as fgb
outdir = Path("gpkg tiles"); outdir.mkdir(exist ok=True)
tile ids = fgb.HTTPReader('https://data.3dbag.nl/v20240420/tile index.fgb',
bbox=(84000, 477000, 86000, 478000))
for tile id in tile ids:
   url = tile id.properties['gpkg download']
   urlretrieve(url, outdir / url.split('/')[-1])
```

Script in:

github.com/3DBAG/3dbag-scripts

- Programmatic access to the 3DBAG data
- Returns cityJSONSeq
- Allows the retrieval of specific buildings and bbox operations
- Not yet OGC-compliant
- Only supported CRS: Amersfoort / RD
 New + NAP height (EPSG:7415)

https://api.3dbag.nl/

Request Single Building:

BAG identifier

https://api.3dbag.nl/collections/pand/items/NL.IMBAG.Pand.0503100000032914

Request All Buildings in a BBox:

__ xmin __ ymin __ xmax __ ymax

https://api.3dbag.nl/collections/pand/items?bbox=85000.00,446700.03,85300.00,447000.00

Instructions in:

api.3dbag.nl/api.html

Request Single Building:

https://api.3dbag.nl/collections/pand/items/NL.IMBAG.Pand.050310000032914



CityJSONSeq

```
"feature": {
  "CityObjects": {
    "NL.IMBAG.Pand.0503100000032914": {
      "attributes": {
        "b3 bag bag overlap": 23.3554954528809,
        "b3 bouwlagen": null,
       "b3_dak_type": "slanted",
"b3_h_dak_50p": 20.1499996185303,
        "b3_h_dak_70p": 21.5,
        "b3_h_dak_max": 52.8300018310547,
        "b3_h_dak_min": 0.93999997615814,
        "b3_h_maaiveld": 0.0020000000949949,
        "b3_kas_warenhuis": false,
        "b3_mutatie_ahn3_ahn4": false,
        "b3_nodata_fractie_ahn3": 0.000949908164329826,
        "b3 nodata_fractie_ahn4": 0.271673738956451,
        "b3_nodata_radius_ahn3": 0.76659369468689,
        "b3_nodata_radius_ahn4": 3.12317109107971,
        "b3_opp_buitenmuur": 19287.86,
        "b3_opp_dak_plat": 2240.14,
        "b3_opp_dak_schuin": 9948.24,
        "b3_opp_grond": 7894.57,
        "b3 opp scheidingsmuur": 1406.73,
        "b3 puntdichtheid_ahn3": 18.9032707214355,
        "b3 puntdichtheid ahn4": 27.572732925415.
        "b3_pw_bron": "AHN3",
        "b3_pw_datum": 2014,
        "b3_pw_selectie_reden": "_HIGHEST_YET_INSUFFICIENT_COVERAGE",
        "b3 reconstructie_onvolledig": false,
        "b3_rmse_lod12": 3.58611083030701,
        "b3_rmse_lod13": 2.86251378059387,
        "b3 rmse lod22": 0.478037446737289,
        "b3_val3dity_lod12": "[]",
        "b3_val3dity_lod13": "[]",
        "b3_val3dity_lod22": "[303]",
        "b3_volume_lod12": 169719.15625,
        "b3 volume lod13": 169433.0625
```

Request Single Building:

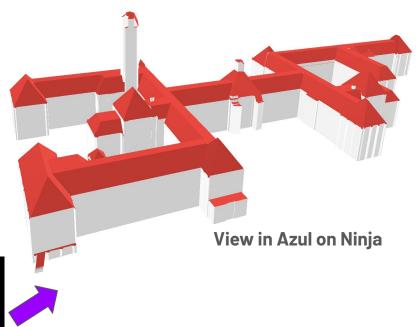
https://api.3dbag.nl/collections/pa nd/items/NL.IMBAG.Pand.050310 0000032914



```
BUILDING_ID = "NL.IMBAG.Pand.0503100000032914"

request = f"https://api.3dbag.nl/collections/pand/items/ {BUILDING_ID}"

with urllib.request.urlopen(request) as response:
    j = json.loads(response.read().decode('utf-8'))
    with open(f"{BUILDING_ID}.city.jsonl", "w") as my_file:
        my_file.write(json.dumps(j["metadata"]) + "\n")
    if "feature" in j:
        my_file.write(json.dumps(j["feature"]) + "\n")
    if "features" in j:
        for f in j["features"]:
        my_file.write(json.dumps(f) + "\n")
```



Request Single Building:

https://api.3dbag.nl/collections/pa nd/items/NL.IMBAG.Pand.050310 0000032914



```
BUILDING_ID = "NL.IMBAG.Pand.0503100000032914"

request = f"https://api.3dbag.nl/collections/pand/items/ {BUILDING_ID}"

with urllib.request.urlopen(request) as response:

j = json.loads(response.read().decode('utf-8'))

with open(f"{BUILDING_ID}.city.jsonl", "w") as my_file:

my_file.write(json.dumps(j["metadata"]) + "\n")

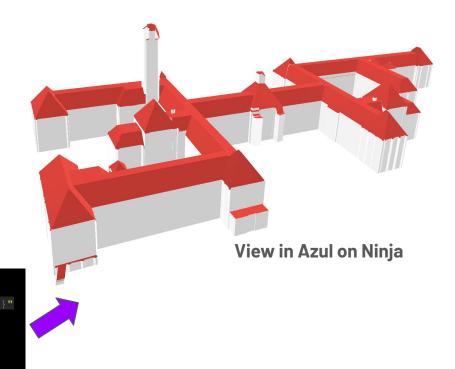
if "feature" in j:

my_file.write(json.dumps(j["feature"]) + "\n")

if "features" in j:

for f in j["features"]:

my_file.write(json.dumps(f) + "\n")
```



Script in:

github.com/3DBAG/3dbag-scripts

New file format: IFC (soon)



Part III - Roadmap & community



The next version of 3DBAG

Next steps?

Currently working on a new 3DBAG version:

- using our improved software pipeline
 - outputs also object without 3D geometry (eg. due to no points)
 - Improved detection glass roofs
- AHN5 pointcloud Update
 - o update buildings west NL

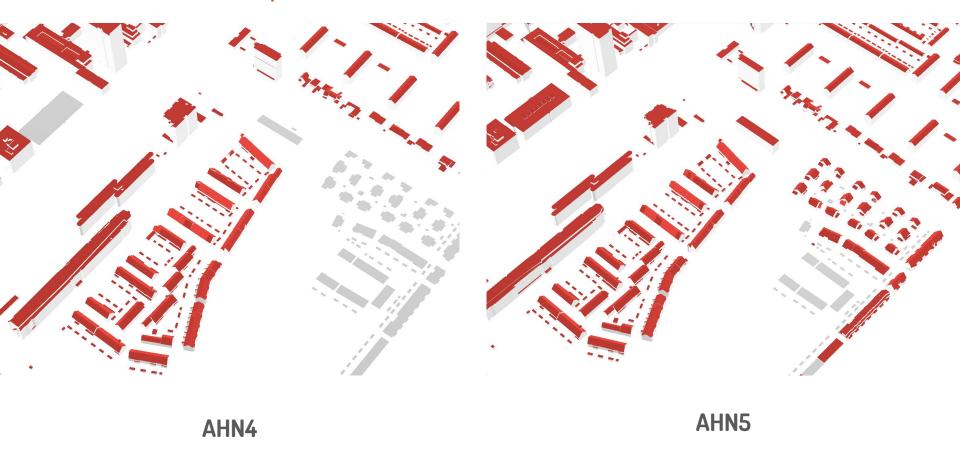
Versions after:

- Add IFC as tile format
- Update 3DBAG webviewer + 3D Tiles
- Improvements reconstruction algorithm
 - Improved plane detection
 - o Better geometry regularisation
 - Improved dormer detection

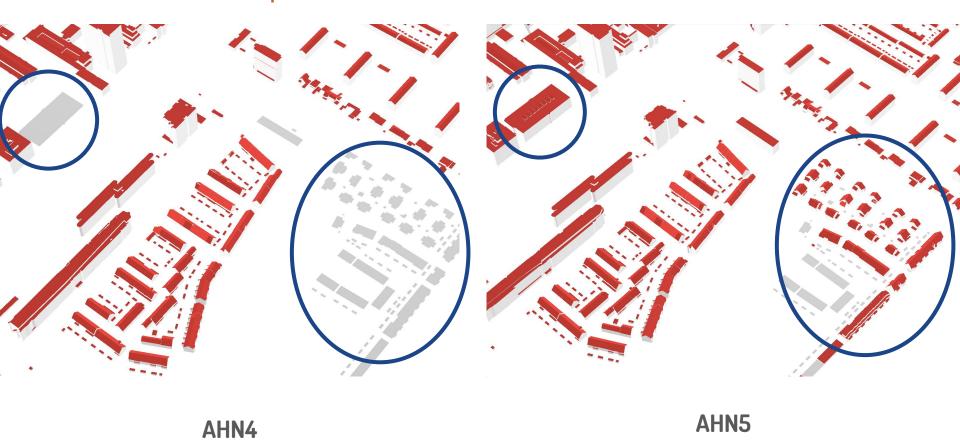




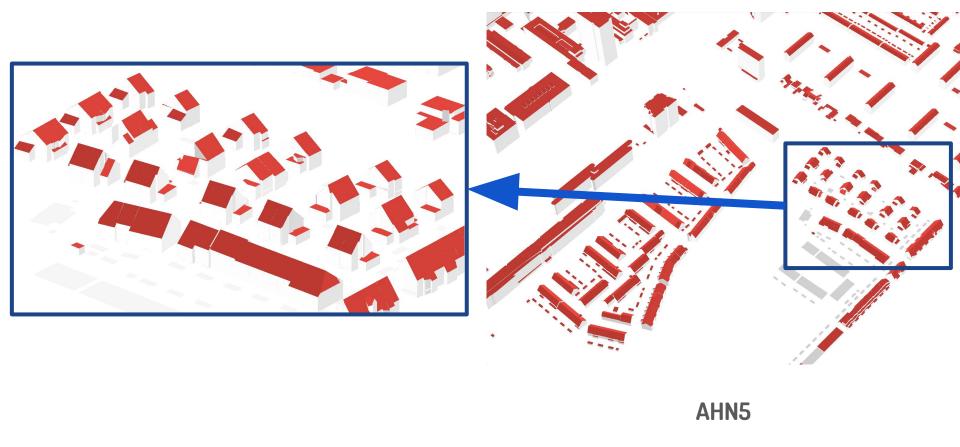
AHN5 sneak preview



AHN5 sneak preview



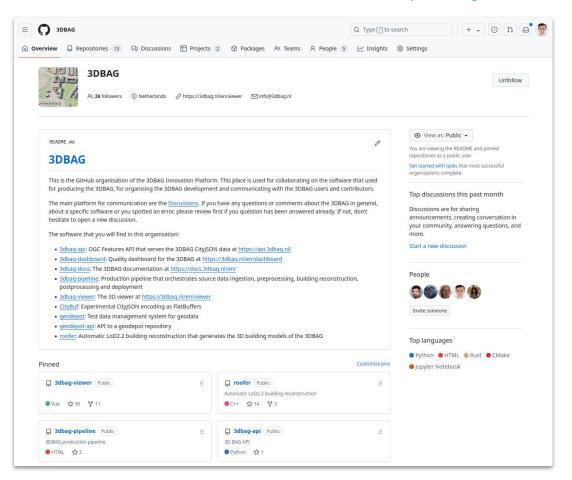
AHN5 sneak preview



3DBAG organisation and contributors

3DBAG on GitHub

https://github.com/3DBAG



We are ready for contributors

- all software Open Source
- permissive licenses (MIT, Apache-2.0, GPLv3)
- independent governance and coordination by Geonovum (3DBAG Innovation Platform)
- public communication (Zulip, GitHub)
- contributor guidelines (in progress)
- public roadmap (in progress)

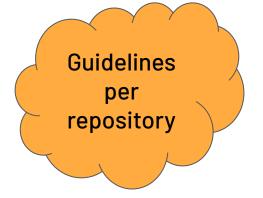
Ways to contribute

- Use the 3DBAG data and report how it goes
- Use the software and report how it goes
- Improve the 3DBAG data documentation
- Improve the software user and developer documentation
- Fix an issue and open a PR
- Spread the word about the 3DBAG

We are looking for sponsors (contact us)

Ways to contribute

- Use the 3DBAG data and report how it goes
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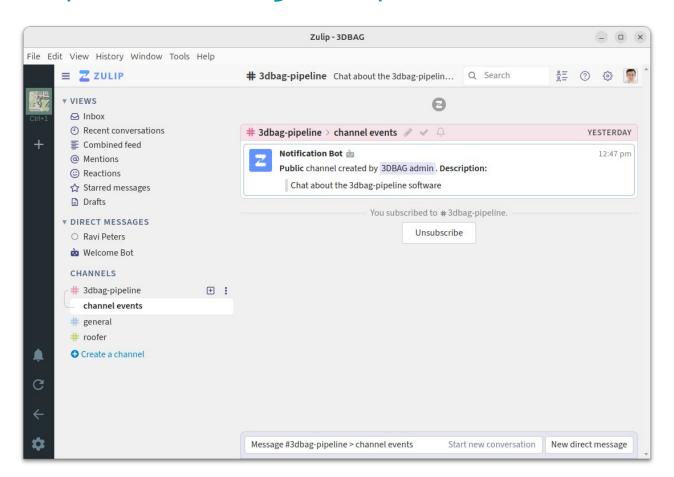
Communication for developers

Newsletter

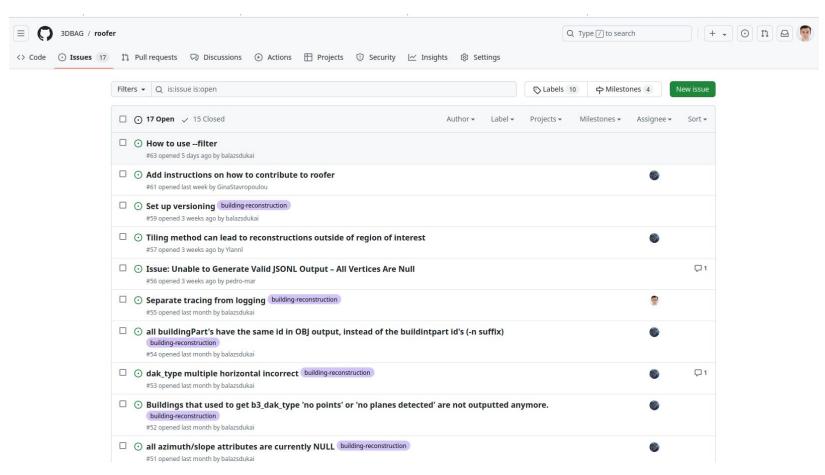


https://tinyurl.com/52dnazfs

Chat - https://3dbag.zulipchat.com



Issues per repository



Thank you!







Register for 3DBAG newsletter:



Time for some feedback...

Join at menti.com | use code | 3905 1921

Closing questions

... to gather some feedback

QA session